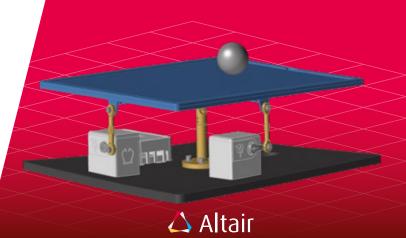


A TRUE DIGITAL TWIN EXPERIENCE

A comprehensive educational kit to teach and learn model-based development with the highest fidelity digital twin simulations.





Balancing a ball on a table in a desired position is one of the most important and classical problems of control theory. Altair, partnering with ACROME, promotes the unique experience of a digital twin mechatronics simulation and hands-on experiment platform to teach and learn model-based controller design concepts with a 3D+1D system co-simulation engine.

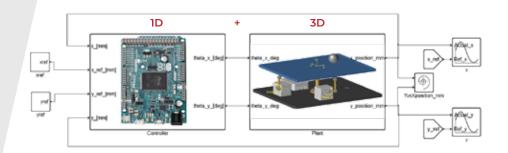
TEACHERS

Prepare your students to hit-the-ground-running in their work as mechatronics engineers!

STUDENTS

Get the premier mechatronics jobs! As an explorer, empower yourself with the next generation engineering tools to innovate better and faster.

FOR THE ULTIMATE MECHATRONICS EDUCATION!



Powered by Altair Activate, an open integration platform for multi-disciplinary system simulations, combining classical 1D block diagrams and system models with 3D motion models.



HANDS-ON, PROJECT-BASED LEARNING WITH DIGITAL TWINS



Hardware-based project



CAE simulation-based project



Plant modeling with no compromises. This Ball Balancing Table allows you to simulate the digital twin in 3D + 1D and compare the results with the real data. The Mechatronics Education Kit seamlessly integrates engineering concepts with actual hardware.

WHAT'S INCLUDED	STARTER KIT ¹	EXPANSION KIT
Hardware + Courseware	\varnothing	\varnothing
'Teaching License' of Software ²	\varnothing	
Initial Setup Help and Training (via web)	\varnothing	

- 1) Only 1 Starter Kit is needed. If you already have the Altair software, you need only purchase Expansion Kits.
- 2) Software License includes: Altair Compose®, Altair Activate®, Altair MotionSolve™ & MotionView™. All software apps can be installed and run on student computers and/or on school computers.

What can be studied with the Starter Kit?

- ◆ System dynamics and automated control concepts
- ◆ Integration of high-fidelity controllers with high-fidelty mechanical plants.
- ◆ Virtual commissioning of real platform via digital twin
- ◆ Optimization of the controller gains with different operating conditions and controller types.







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